



1  
00:00:26,180 --> 00:00:23,660  
I'm Lori Meggs and I'm bill hubscher

2  
00:00:27,590 --> 00:00:26,190  
welcome to focus on Marshall on today's

3  
00:00:29,210 --> 00:00:27,600  
program we're going to show you a lab

4  
00:00:31,850 --> 00:00:29,220  
here at Marshall that can take this and

5  
00:00:38,350 --> 00:00:31,860  
build this the first let's go for a ride

6  
00:00:38,360 --> 00:00:45,369  
and we are about 400 to head over to see

7  
00:00:49,190 --> 00:00:47,660  
these are some of the exciting new

8  
00:00:51,049 --> 00:00:49,200  
images of the space shuttle during

9  
00:00:52,550 --> 00:00:51,059  
launch we're here now in the imaging

10  
00:00:54,140 --> 00:00:52,560  
system lab with Eric quarter has been

11  
00:00:55,940 --> 00:00:54,150  
instrumental in developing some of those

12  
00:00:58,190 --> 00:00:55,950  
systems Eric tell me what you do in this

13  
00:00:59,930 --> 00:00:58,200

lab well during the last 3 years our

14

00:01:02,030 --> 00:00:59,940

primary focus has been on developing

15

00:01:04,760 --> 00:01:02,040

requirements and a design to look at the

16

00:01:06,530 --> 00:01:04,770

shuttle overall vehicle during flight

17

00:01:08,240 --> 00:01:06,540

one of the primary designs that we

18

00:01:09,920 --> 00:01:08,250

worked on is the external tank camera

19

00:01:11,660 --> 00:01:09,930

which you've had views of that everyone

20

00:01:14,389 --> 00:01:11,670

is seeing and with the next upcoming

21

00:01:16,490 --> 00:01:14,399

flight we have two SRB cameras on each

22

00:01:18,139 --> 00:01:16,500

solid booster so we'll have a total of

23

00:01:20,930 --> 00:01:18,149

five cameras viewing the shoulder and

24

00:01:22,730 --> 00:01:20,940

flight primary focus is to look the

25

00:01:24,260 --> 00:01:22,740

overall health of the vehicle in

26  
00:01:26,029 --> 00:01:24,270  
particular we're looking at the wing

27  
00:01:28,040 --> 00:01:26,039  
leading edges and we're also looking at

28  
00:01:29,930 --> 00:01:28,050  
the bipod region do you have any

29  
00:01:31,790 --> 00:01:29,940  
hardware you can show us yes we do have

30  
00:01:33,499 --> 00:01:31,800  
an external tank camera that we can look

31  
00:01:35,029 --> 00:01:33,509  
at we have models of the solid rocket

32  
00:01:37,490 --> 00:01:35,039  
booster camera that we can view as well

33  
00:01:39,800 --> 00:01:37,500  
alright let's take a look we're joined

34  
00:01:41,240 --> 00:01:39,810  
now by Jeremy Meyers who has a table

35  
00:01:42,740 --> 00:01:41,250  
full of hardware is going to show us

36  
00:01:44,270 --> 00:01:42,750  
we're going to start with the camera

37  
00:01:45,980 --> 00:01:44,280  
that was instrumental in the return to

38  
00:01:48,410 --> 00:01:45,990

flight effort right Jeremy that's right

39

00:01:51,980 --> 00:01:48,420

this camera here is an example of the

40

00:01:53,960 --> 00:01:51,990

camera which flew on sts-114 and this

41

00:01:56,300 --> 00:01:53,970

unit here was actually what caught the

42

00:01:58,249 --> 00:01:56,310

debris and was used by the video

43

00:02:00,949 --> 00:01:58,259

analysts to understand what happened

44

00:02:02,900 --> 00:02:00,959

post flight we as a group here have

45

00:02:04,460 --> 00:02:02,910

worked with lockheed martin and

46

00:02:08,350 --> 00:02:04,470

developing what the requirements needed

47

00:02:10,820 --> 00:02:08,360

to be also we worked with evie 12 and

48

00:02:12,559 --> 00:02:10,830

determined what the field of view would

49

00:02:15,650 --> 00:02:12,569

be they can do modeling within that

50

00:02:17,479 --> 00:02:15,660

group so by working as a team through

51  
00:02:20,089 --> 00:02:17,489  
with all these organizations we were

52  
00:02:22,160 --> 00:02:20,099  
able to have a system which actually

53  
00:02:25,550 --> 00:02:22,170  
ended up being imaging solution of the

54  
00:02:26,839 --> 00:02:25,560  
year in 2006 you've got a couple of

55  
00:02:28,090 --> 00:02:26,849  
other newer cameras here they're going

56  
00:02:30,460 --> 00:02:28,100  
to fly on the next shuttle

57  
00:02:32,110 --> 00:02:30,470  
as well right that's right during the

58  
00:02:34,360 --> 00:02:32,120  
next flight we're going to have cameras

59  
00:02:36,820 --> 00:02:34,370  
on the SRB and we've been working with

60  
00:02:40,000 --> 00:02:36,830  
USA to develop those same requirements

61  
00:02:42,310 --> 00:02:40,010  
to model fill the view with EV 12 and

62  
00:02:43,360 --> 00:02:42,320  
going through that same process and

63  
00:02:46,240 --> 00:02:43,370

we're going to have a camera that's

64

00:02:48,730 --> 00:02:46,250

going to be on the aft of the SRB as

65

00:02:50,170 --> 00:02:48,740

well as the forward of the SRB looking

66

00:02:52,510 --> 00:02:50,180

at the shuttle and what about the

67

00:02:55,000 --> 00:02:52,520

housing for this one well of course we

68

00:02:56,770 --> 00:02:55,010

have to rehouse these to harden them and

69

00:02:58,420 --> 00:02:56,780

there's a process that's gone through

70

00:02:59,770 --> 00:02:58,430

that to withstand the thermal

71

00:03:02,980 --> 00:02:59,780

environments because these are on the

72

00:03:04,540 --> 00:03:02,990

outside of the vehicle now you're also

73

00:03:06,220 --> 00:03:04,550

working on cameras for the next

74

00:03:08,170 --> 00:03:06,230

generation of space vehicles what we

75

00:03:11,530 --> 00:03:08,180

have over here well we're also looking

76  
00:03:13,210 --> 00:03:11,540  
at developing requirements and looking

77  
00:03:17,110 --> 00:03:13,220  
at various camera systems which will be

78  
00:03:18,670 --> 00:03:17,120  
able to fly on the next vehicle leave

79  
00:03:20,830 --> 00:03:18,680  
you have a really small one there too

80  
00:03:22,840 --> 00:03:20,840  
that's right this is an example of a

81  
00:03:25,780 --> 00:03:22,850  
small camera that might have a possible

82  
00:03:28,060 --> 00:03:25,790  
solution there's also higher resolution

83  
00:03:29,470 --> 00:03:28,070  
cameras so there's all kinds of things

84  
00:03:31,330 --> 00:03:29,480  
you have to consider as far as

85  
00:03:34,180 --> 00:03:31,340  
requirements what's the best solution

86  
00:03:35,710 --> 00:03:34,190  
what will fulfill the needs for NASA in

87  
00:03:37,870 --> 00:03:35,720  
the future then you can get that one in

88  
00:03:39,160 --> 00:03:37,880

very hard to reach places that's right

89

00:03:41,650 --> 00:03:39,170

what about these two cameras you have

90

00:03:44,140 --> 00:03:41,660

melted here well another possibility is

91

00:03:47,230 --> 00:03:44,150

to develop a stereo pair and that allows

92

00:03:50,380 --> 00:03:47,240

you to measure accurately wear something

93

00:03:52,990 --> 00:03:50,390

that you see is in space also we have

94

00:03:55,360 --> 00:03:53,000

GPS systems which is allows us to add

95

00:03:57,670 --> 00:03:55,370

Tommy and that allows you to look at

96

00:03:59,650 --> 00:03:57,680

different cameras and to link up what

97

00:04:01,330 --> 00:03:59,660

you're looking at at the same time you

98

00:04:03,550 --> 00:04:01,340

also have this black box to move from

99

00:04:06,040 --> 00:04:03,560

videotape to pure digital recording

100

00:04:07,900 --> 00:04:06,050

right this is an example of another

101  
00:04:09,910 --> 00:04:07,910  
project that the group here is working

102  
00:04:13,420 --> 00:04:09,920  
on and this flies on a sounding rocket

103  
00:04:15,280 --> 00:04:13,430  
but this is a video recorder and it's a

104  
00:04:17,050 --> 00:04:15,290  
digital video recorder so basically you

105  
00:04:20,349 --> 00:04:17,060  
could have camera systems coming in and

106  
00:04:22,000 --> 00:04:20,359  
recording that real-time Jeremy thanks

107  
00:04:23,890 --> 00:04:22,010  
very much let's head back over to Eric

108  
00:04:25,540 --> 00:04:23,900  
and Lori we're back here with Eric in

109  
00:04:26,770 --> 00:04:25,550  
the image characterization lab and this

110  
00:04:28,630 --> 00:04:26,780  
is where you actually look at the

111  
00:04:30,310 --> 00:04:28,640  
performance of the camera that's correct

112  
00:04:32,050 --> 00:04:30,320  
we take the camera that we've design we

113  
00:04:33,700 --> 00:04:32,060

bring it in here we look at the distinct

114

00:04:34,980 --> 00:04:33,710

Slyke lens distortion a single noise

115

00:04:37,410 --> 00:04:34,990

ratio

116

00:04:38,880 --> 00:04:37,420

from that data we utilize that to look

117

00:04:40,470 --> 00:04:38,890

at the shuttle data that we get back

118

00:04:42,120 --> 00:04:40,480

from the external tank camera for

119

00:04:43,560 --> 00:04:42,130

instance and we can determine size of

120

00:04:46,830 --> 00:04:43,570

objects that are in the field of you and

121

00:04:48,510 --> 00:04:46,840

that gives us a nice indian system all

122

00:04:49,830 --> 00:04:48,520

right we can't wait to see the next

123

00:04:50,910 --> 00:04:49,840

images that are on the next shuttle